

Modelling the radiation efficiency of orthotropic cross-laminated timber plates with simply-supported boundaries

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Abstract

In this paper two prediction models to evaluate the radiation efficiency of orthotropic plates, developed with different approaches, are presented. A sound radiation model, based on an analytical/modal approach, is developed for a thin orthotropic plate, with the principal directions aligned with the edges. The model allows to consider the contribution of each mode, either resonant or non-resonant, as well as the influence of fluid loading on the plate dynamic response and on sound radiation. Moreover, a statistical model to evaluate the average radiation efficiency, based on a non-modal approach, which only considers the contribution of resonant modes, is presented. These two models have been used in order to predict the radiation efficiency of orthotropic cross-laminated timber (CLT) plates. CLT is an engineered wood material constituted by an odd number of lumber beams glued together, which have become very popular in the last twenty years in the building construction market. Due to their layered structure, CLT plates might exhibit a highly orthotropic behaviour. Both prediction models are validated by comparing the simulated results with the experimental radiation efficiency, obtained by means of vibro-acoustic measurements on three CLT plates. Finally, the influence of fluid loading on sound power radiated by CLT plates is investigated.

Keywords: radiation efficiency, orthotropic plate, cross-laminated timber, fluid-loading influence

1. Introduction

2 Noise reduction is nowadays a main concern as much in the automotive or aerospace industry
3 as in building construction and in many other fields. In order to design structures that provide
4 good sound insulation it is fundamental to characterise how the vibrating elements radiate sound.
5 Sound radiation has been the object of an increasing interest during the last half century and the
6 physics behind this mechanism is well known. However, from an engineering point of view,
7 the computation of the sound power radiated by a vibrating surface is still a highly demanding
8 task compared to pure vibrational problems. In order to provide reliable alternatives to finite
9 elements (FE) and boundary elements methods (BEM), which usually require a considerable

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10 computational effort, many formulations to predict the radiated sound power have been proposed
11 by several authors. These prediction models provide approximated results with wide-ranging
12 levels of accuracy. They have been developed by using different approaches and under differ-
13 ent basic assumptions, upon which depends their suitability for each specific problem. Based
14 on a *non-modal approach*, the modal-average radiation efficiency due to the contribution of the
15 resonant vibrational field can be evaluated [1]. On the other hand, using a *modal approach* the
16 radiation efficiency is approximated by taking into account all the in-vacuo single modes within
17 the frequency range [2]. In order to consider the influence of cross-modal coupling, different *an-*
18 *alytical formulations* have been developed using either the far field [3], or the near-field approach
19 [4]; the latter also takes into account the fluid loading effect. An extensive and more detailed bib-
20 liographic analysis of the prediction models to compute sound radiation was presented by Atalla
21 and Nicolas in 1994 [5]. Later in the same decade Nelisse [6] proposed a generalized model for
22 the acoustic radiation from baffled and unbaffled homogeneous plates, with arbitrary boundary
23 conditions. The same approach was also used by Foin to develop a tool to predict the acoustic
24 and structural vibration response of sandwich plates [7]. More recently Mejdı and Atalla pre-
25 sented a semi-analytical model to numerically investigate the vibro-acoustic response of stiffened
26 plates [8], while Legault analysed orthogonally ribbed plates by means of a periodic theory [9].
27 Rhazi and Atalla used simple and quick tools, such as statistical energy analysis and the trans-
28 fer matrix method, to estimate the vibro-acoustic response of mechanically-excited multilayer
29 structures [10]. Davy developed a two dimensional strip analytic approximation to compute the
30 forced radiation efficiency of acoustically excited finite size panels [11]. Davy also presented
31 an approximation method to calculate both the real and the imaginary part of the single-side
32 specific forced radiation impedance of a rectangular panel [12]. The possibility to consider both
33 the resonant and non resonant contribution, in the case of an acoustically excited plate, and the
34 near-field contribution in the case of mechanical point excitation, was also introduced by Davy
35 in a recently published paper [13].

36 Two models are presented in this paper; they have been implemented in order to estimate the
37 radiation efficiency of mechanically excited orthotropic panels, such as cross-laminated timber
38 plates used in buildings. Cross-laminated timber solid wood panels, commonly known as CLT,
39 consist of an odd number of layers of lumber beams glued together, alternating the fibres orienta-
40 tion of adjoining plies orthogonally. This engineered wood material has gained a growing success
41 in the construction market over the last two decades, especially in Europe and North America.
42 In fact in recent years, CLT has also attracted the interest of acousticians and researchers who
43 have carried out experimental investigations on these structures [14–18]. Nowadays, CLT struc-
44 tures represent a valuable alternative to traditional construction materials. They provide good
45 structural stability, fulfil the safety requirements and allow to reduce construction time, since
46 they can be completely prefabricated and then assembled at the construction site. The drawback
47 of this construction technology is arguably the poor sound insulation provided by CLT panels,
48 due to their low density combined with a relatively high stiffness. During the design process it is
49 necessary to acoustically optimize the CLT elements in order to improve the sound insulation per-
50 formance and meet the acoustic requirements for buildings [19]. Due to their layered sub-structure
51 and the properties of the wood material, CLT plates generally exhibit an orthotropic behaviour
52 [20, 21], which means that they have different elastic properties along mutually perpendicular
53 directions. CLT panels can be investigated as 3D orthotropic plates. This approach, however,
54 would involve a rather tedious and complex analysis with nine independent elastic constants to
55 be known: i.e. three elastic moduli and three Poisson’s ratios associated with the the principal
56 directions and three shear moduli. In order to define more usable models, the thin plate theory is

57 here adopted, since it greatly simplifies the problem, describing the orthotropic constitutive rela-
58 tionship by means of only five independent constants. However, in order to take into account the
59 influence of rotatory inertia and shear deformation, which are neglected in the thin plate theory
60 but might be significant especially in the high frequency range, the CLT panels are described by
61 means of apparent frequency-dependent elastic properties, as further discussed below.

62 In the next section the numerical models to predict the radiation efficiency of orthotropic
63 plates are introduced. At first, an analytical formulation for a thin orthotropic plate is derived,
64 by following the general approach, based on a variational formulation, proposed by Nelisse [6].
65 Then a simplified modal-average approach to compute the orthotropic radiation efficiency, based
66 on more restrictive assumptions, is described. Both models have been validated with the exper-
67 imental radiation efficiency evaluated for three different CLT plates, as described in section 3.
68 The main results are presented and discussed in section 4.

69 2. Prediction models for an orthotropic plate

70 The radiation efficiency σ is defined as the ratio between the sound power W_{rad} actually
71 radiated by a vibrating elastic structure and the sound power that would theoretically be radiated
72 by a rigid piston of equal surface area S vibrating with the same mean square velocity $\langle v^2 \rangle_{s,t}$,
73 where the subscript $_{s,t}$ indicates time and spatial average, multiplied by the characteristic air
74 impedance $Z_0 = \rho_0 c_0$:

$$75 \quad \sigma = \frac{W_{rad}}{\rho_0 c_0 S \langle v^2 \rangle_{s,t}}. \quad (1)$$

76 where ρ_0 is the density of the fluid medium and c_0 the speed of sound within the fluid. This
77 acoustic descriptor, characterising the capability of a vibrating structure to transfer the vibra-
78 tional energy to the surrounding fluid as sound energy, represents important input data, required
79 in the greatest part of building acoustics prediction models [22–26]. In this section two models to
80 evaluate the radiation efficiency of an orthotropic rectangular plate are presented. They are based
81 on different assumptions and developed following distinct approaches. An analytical/modal-
82 based approach is derived, either considering or neglecting the influence of fluid loading. Then
83 a modal-average model, which may be useful within the statistical energy analysis (SEA) frame-
84 work, is presented.

85 Both models assume the validity of thin plate theory. However, as the frequency increases
86 and the structural wavelength approaches the panel thickness, rotational inertia and shear de-
87 formation effects start to have a significant influence on the plate dynamics. For this reason,
88 apparent frequency-dependent stiffness properties have been introduced in order to adopt low-
89 order theories while considering several effects which take part in the flexural motion, such as
90 shear deformation, rotatory inertia, viscoelasticity and the layered substructure. The possibility
91 to adopt such a homogenisation approach, commonly used to investigate sandwich structures
92 [27–29], also to CLT panels has already been successfully investigated and discussed by other
93 authors in previous studies [20, 30].

94 2.1. Modal based radiation and fluid-loading

95 Let us consider a rectangular thin orthotropic plate, with the principal axes aligned with the
96 edges, lying in the $x - y$ plane and inserted in a coplanar rigid baffle, as shown in Figure 1.

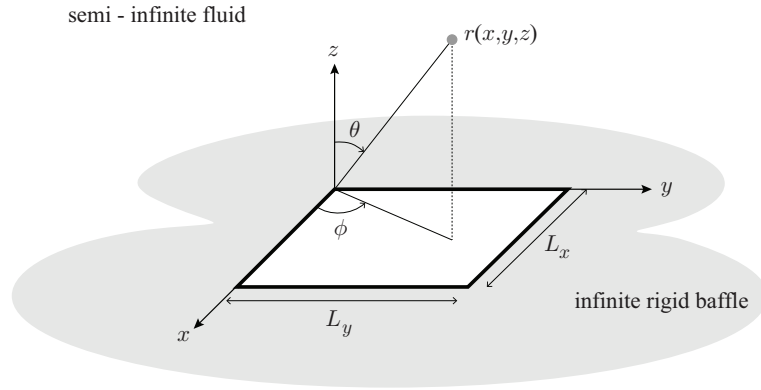


Figure 1: Elastic thin orthotropic plate inserted in a infinite rigid baffle, radiating sound energy in a semi-infinite fluid domain $z > 0$.

97 The equation of motion of such a thin orthotropic plate, undergoing free flexural vibrations, is
 98 governed by the fourth-order in space and second-order in time differential equation:

$$99 \quad D_x \frac{\partial^4 w}{\partial x^4} + 2B \frac{\partial^4 w}{\partial x^2 \partial y^2} + D_y \frac{\partial^4 w}{\partial y^4} = \rho h \frac{\partial^2 w}{\partial t^2}. \quad (2)$$

100 The bending stiffness along the principal directions, D_x and D_y , and the effective torsional stiff-
 101 ness B , are a function of elastic and in-plane shear moduli E_x , E_y and G_{xy} :

$$102 \quad D_x = \frac{E_x h^3}{12(1 - \nu_{xy} \nu_{yx})}; \quad D_y = \frac{E_y h^3}{12(1 - \nu_{xy} \nu_{yx})}; \quad (3)$$

$$103 \quad B = \frac{\nu_{xy} D_y}{2} + \frac{\nu_{yx} D_x}{2} + 2G_{xy} \frac{h^3}{12}. \quad (4)$$

105 The elastic constants ν_{xy} and ν_{yx} are related to the geometrical configuration of the orthotropic
 106 plate [31]. According to Betti's reciprocal theorem, the bending stiffness along the two principal
 107 directions satisfies the relationship [32]:

$$108 \quad \nu_{yx} D_x = \nu_{xy} D_y. \quad (5)$$

109 A sound radiation model for an orthotropic thin plate has been developed using a general
 110 approach based on Hamilton's variational principle. The solution for the plate's transverse dis-
 111 placement w can be derived following the generalised approach proposed by Nelisse [6] to evalu-
 112 ate the sound power radiated by rectangular isotropic plates immersed in a fluid. The plate's
 113 transverse displacement $w(x, y, t)$ is approximated by a linear sum of admissible trial functions
 114 $\psi_{mn}(x, y)$:

$$115 \quad w(x, y, t) = \sum_m^M \sum_n^N a_{mn} \psi_{mn}(x, y) e^{i\omega t}, \quad (6)$$

116 where a_{mn} represents the unknown amplitude of the transverse displacement associated with the
 117 mode (m, n) . Assuming simply supported boundary conditions at all edges, sine functions can be
 118 used as trial functions $\psi_{mn}(x, y)$, providing numerical stability in the computation [33]:

$$119 \quad \psi_{mn}(x, y) = \sin\left(\frac{m\pi x}{L_x}\right) \sin\left(\frac{n\pi y}{L_y}\right). \quad (7)$$

120 Assuming a harmonic time dependence of the kind $e^{i\omega t}$, the plate steady state equation of motion
 121 for forced vibration can be expressed, for a given angular frequency ω , as a linear matrix system:

$$122 \quad \left(-\omega^2 M_{mnpq} + K_{mnpq} + i\omega Z_{mnpq}\right) a_{mn} = f_{mn}, \quad (8)$$

123 where M_{mnpq} are the mass matrix coefficients, K_{mnpq} the stiffness matrix coefficients, Z_{mnpq} are
 124 the coefficients of the impedance matrix, while f_{mn} are the coefficients of the external force
 125 vector. The amplitude coefficients a_{mn} of the transverse displacement vector \mathbf{w} represents the
 126 only unknown of the system.

127 The stiffness matrix takes into account the orthotropic behaviour of the structure and its
 128 coefficients can generally be formulated as a double integral over the plate surface S :

$$129 \quad K_{mnpq} = \int_0^{L_y} \int_0^{L_x} \left[D_x \frac{\partial^2}{\partial x^2} \psi_{mn}(x, y) \frac{\partial^2}{\partial x^2} \psi_{pq}(x, y) + D_y \frac{\partial^2}{\partial y^2} \psi_{mn}(x, y) \frac{\partial^2}{\partial y^2} \psi_{pq}(x, y) \right. \\
 + \nu_{yx} D_x \frac{\partial^2}{\partial x^2} \psi_{mn}(x, y) \frac{\partial^2}{\partial y^2} \psi_{pq}(x, y) + \nu_{xy} D_y \frac{\partial^2}{\partial y^2} \psi_{mn}(x, y) \frac{\partial^2}{\partial x^2} \psi_{pq}(x, y) \\
 \left. + 4G_{xy} \frac{h^3}{12} \frac{\partial^2}{\partial x \partial y} \psi_{mn}(x, y) \frac{\partial^2}{\partial x \partial y} \psi_{pq}(x, y) \right] dS. \quad (9)$$

130 In Appendix A, the two-fold integral is reduced to a simpler and computationally faster formu-
 131 lation, under the assumption of simply-supported boundaries.

132 The mass matrix coefficients, as for an isotropic simply-supported plate, are given by:

$$133 \quad M_{mnpq} = \rho h \int_0^{L_x} \int_0^{L_y} \sin\left(\frac{m\pi x}{L_x}\right) \sin\left(\frac{n\pi y}{L_y}\right) \sin\left(\frac{p\pi x}{L_x}\right) \sin\left(\frac{q\pi y}{L_y}\right) dS. \quad (10)$$

134 However, due to the orthogonality property of the eigenfunctions, Eq. (10) reduces to:

$$135 \quad M_{mnpq} = \begin{cases} M_{mn} = \frac{\rho h L_x L_y}{4}; & \text{if } m = p \text{ and } n = q, \\ 0; & \text{if } m \neq p \text{ or } n \neq q. \end{cases} \quad (11)$$

136 The radiation impedance \mathbf{Z} is a sparse matrix of complex numbers. Its coefficients can be ex-
 137 pressed in terms of its real and imaginary parts, the radiation resistance \mathbf{R} and radiation reactance
 138 \mathbf{X} respectively:

$$139 \quad Z_{mnpq} = R_{mnpq} + iX_{mnpq}. \quad (12)$$

140 The computation of the radiation impedance coefficients involves a four-fold integral to be
 141 solved:

$$142 \quad Z_{mnpq} = i\omega\rho_0 \int_S \int_S \psi_{mn}(x, y) G(x, y, 0, \bar{x}, \bar{y}, 0) \psi_{pq}(\bar{x}, \bar{y}) dS d\bar{S}. \quad (13)$$

143 The Green's function $G(x, y, 0, \bar{x}, \bar{y}, 0)$ for the semi-infinite space is given by:

$$144 \quad G(x, y, 0, \bar{x}, \bar{y}, 0) = \frac{\exp\left(-ik_0 \sqrt{(x - \bar{x})^2 + (y - \bar{y})^2}\right)}{2\pi \sqrt{(x - \bar{x})^2 + (y - \bar{y})^2}}. \quad (14)$$

145 Eq. (13) has been reduced to a two-fold integral using the approach proposed by Sandman [4]
146 and Nelisse [6], although by using different integration limits, as shown in Appendix B.

147 When the surrounding fluid has a low inertia compared to the radiating structure, the fluid
148 loading and the modal cross-coupling are usually assumed to be negligible, as also shown in
149 Appendix B. The coefficients of the radiation impedance matrix can thus be approximated by
150 considering only the self-radiation resistance R_{mn} , i.e. the real part of the diagonal terms. The
151 self-radiation resistance is proportional to the modal radiation efficiency σ_{mn} according to the
152 relationship:

$$153 \quad R_{mn} = n_{mn} \rho_0 c_0 S \sigma_{mn}, \quad (15)$$

154 where n_{mn} represents the norm of the mode, which in the case of simply-supported boundaries:
155 $n_{mn} = 0.25$. The modal radiation efficiency σ_{mn} can be determined by using Wallace's formula-
156 tion [34]:

$$157 \quad \sigma_{mn} = \frac{64k_0^2 L_x L_y}{\pi^6 m^2 n^2} \int_0^{\pi/2} \int_0^{\pi/2} \left\{ \frac{\Gamma\left(\frac{\alpha}{2}\right) \Lambda\left(\frac{\beta}{2}\right)}{\left[\left(\frac{\alpha}{m\pi}\right)^2 - 1\right] \left[\left(\frac{\beta}{n\pi}\right)^2 - 1\right]} \right\}^2 \sin \theta \, d\theta d\phi, \quad (16)$$

158 in which $\alpha = k_0 L_x \sin \theta \cos \phi$ and $\beta = k_0 L_y \sin \theta \sin \phi$. The function Γ is \cos if m is an odd integer,
159 while it is \sin if m is an even integer. The trigonometric functions for Λ are chosen analogously
160 with respect to the integer n . The integration is performed over the propagation angle of the
161 structural wave ϕ and over the angle of propagation θ of the acoustic wave in the fluid medium.

162 The coefficients associated with the external excitation are given, assuming a harmonic point-
163 force, by:

$$164 \quad f_{mn} = F_0 \psi_{mn}(x_S, y_S), \quad (17)$$

165 where F_0 represents an arbitrary amplitude of the point-force that drives the plate in the position
166 (x_S, y_S) .

167 Knowing the coefficients of the mass, stiffness, and radiation impedance matrix and of the
168 external force vector, the amplitude of the plate's transverse displacement vector a_{mn} can be
169 computed by solving a set of linear algebraic equations:

$$170 \quad a_{mn} = A_{mnpq} f_{mn}, \quad (18)$$

171 where the admittance matrix \mathbf{A} is obtained from the inversion of the matrices between parenthe-
172 ses on the left - hand side of equation (8) as:

$$173 \quad A_{mnpq} = \left(-\omega^2 M_{mnpq} + K_{mnpq} + i\omega Z_{mnpq}\right)^{-1}. \quad (19)$$

174 In order to numerically perform the matrix inversion, for each investigated frequency ω , it is
175 necessary to re-arrange the multi-dimensional matrices \mathbf{M} , \mathbf{K} and \mathbf{Z} , in two dimensions.

176 By solving Eq. (18) it is possible to compute the vibro-acoustic indicators as a function of
 177 the plate's transverse displacement w . The mean square vibration velocity of the plate is given
 178 by:

$$179 \quad \langle v^2 \rangle = \frac{\omega^2}{8} \sum_m \sum_n |a_{mn}|^2. \quad (20)$$

180 The radiated sound power is computed by integrating the active sound intensity over the plate
 181 surface:

$$182 \quad W_{\text{rad}} = \frac{\omega^2}{2} \sum_m \sum_n \sum_p \sum_q a_{mn} \text{Re} [Z_{mnpq}] a_{pq}^*, \quad (21)$$

183 where the superscript * denotes the complex conjugate value. The orthotropic plate radiation
 184 efficiency can be determined according to Eq. (1).

185 2.2. Modal-average radiation efficiency

186 As the number of modes within the frequency band increases, it might be more convenient
 187 to derive an average radiation efficiency, rather than consider the radiation of each single mode.
 188 The modal-average radiation efficiency is an acoustic descriptor, usually expressed in one-third
 189 octave bands, often required in building acoustics, either in SEA-based prediction models and
 190 when a broad band excitation is involved. A statistical radiation efficiency model was imple-
 191 mented, based on the modal-average formulations proposed by Ghinet and Atalla [35] and by
 192 Anderson and Bratos-Anderson [36], using as input data frequency-dependent stiffness proper-
 193 ties. Such a statistical approach requires some additional assumptions: (i) high modal density
 194 and modal overlap over the entire frequency range in order to treat the discrete distribution of
 195 modes as a continuous function; (ii) the sound power is only radiated by resonant modes; (iii)
 196 the resonant modes are uncorrelated; (iv) equipartition of modal energy can be applied: all the
 197 modes within the frequency band have the same vibrational energy. The average radiation effi-
 198 ciency of a thin orthotropic baffled panel can be computed by weighting the direction dependent
 199 radiation efficiency $\sigma(\omega, \phi)$ by the plate modal density n_d :

$$200 \quad \sigma_{\text{ortho}}(\omega) = \frac{L_x L_y}{\pi^2 n_d} \int_0^{\pi/2} \sigma(\omega, \phi) k_B \frac{\partial k_B}{\partial \omega} d\phi. \quad (22)$$

201 The radiation efficiency $\sigma(\omega, \phi)$ is computed, at a given angular frequency ω and propagation
 202 angle ϕ , using Leppington's asymptotic formulations [37, 38], developed for three different
 203 frequency ranges, with respect to the coincidence condition, which occurs when the acoustic
 204 wavenumber k_0 matches the wavenumber of the structural bending wave propagating in the plate
 205 k_B :

$$206 \quad \begin{aligned} \mu < 1 - \delta & : \text{above the critical condition;} \\ \mu = 1 \pm \delta & : \text{near the critical condition;} \\ \mu > 1 + \delta & : \text{below the critical condition;} \end{aligned}$$

207 where μ is the dimensionless bending wavenumber defined as the ratio: $\mu = \frac{k_B}{k_0}$. Below the critical
 208 condition the acoustic wavelength λ_0 is much bigger than the bending wavelength λ_B , vice-versa
 209 the acoustic wavenumber is smaller than the bending wavenumber. Air particles move parallel
 210 to the plate surface and compensate the oscillating areas associated with high and low pressure.
 211 Sound is only radiated at the edges, and at other discontinuities, where the pressure change cannot
 212 be fully compensated by the moving air. The radiation efficiency is much smaller than unity in

213 this frequency range. Above the critical condition sound is radiated uniformly from the plate
 214 surface, like in the case of a piston source; therefore, the radiation efficiency approaches unity.
 215 The bending wavenumber k_B always fits the trace wavenumber of an acoustic wave propagating
 216 away from the surface at a certain angle: $k_B = k_0 \sin \theta$. At coincidence, $\mu = 1$, the plate radiates
 217 sound more efficiently than a piston source and σ exceeds unity. The complete set of equations
 218 to compute the asymptotic radiation efficiency is given in Leppington's papers [37, 38] where
 219 it was developed for an isotropic homogeneous plate. However, those papers do not provide
 220 information on how factor δ , which defines the frequency limits of the near-coincidence region,
 221 should be determined. The procedure we developed in order to determine the three frequency
 222 ranges for which Leppington's equations are defined was implemented for a discrete number of
 223 angles within the interval $0 \leq \phi \leq \pi/2$ and is described in Appendix C. Due to the orthotropic
 224 nature of the CLT plate, the bending wave velocity depends upon the propagation direction of the
 225 structural wave. Therefore, a direction-dependent bending wavenumber has to be considered. At
 226 any propagation angle ϕ , the direction-dependent bending wavenumber $k_B(\phi)$ can be estimated
 227 from the wavenumber components along the principal directions $k_{B,x}$ and $k_{B,y}$, by applying a
 228 well-established orthotropic elliptic model [39]:

$$229 \quad k_B(\phi) = \sqrt{(k_{B,x} \cos \phi)^2 + (k_{B,y} \sin \phi)^2}. \quad (23)$$

230 For a thin orthotropic rectangular plate the modal density n_d , which describes the number of
 231 modes per Hertz, is given by:

$$232 \quad n_d = \frac{L_x L_y \sqrt{\rho h}}{2\pi^2} \int_0^{\pi/2} \sqrt{\frac{1}{D(\phi)}} d\phi. \quad (24)$$

233 The direction-dependent bending stiffness $D(\phi)$ can be approximated for each propagation angle
 234 ϕ at a given angular frequency ω as:

$$235 \quad D(\phi) = \frac{\omega^2 \rho h}{k_B^4(\phi)}. \quad (25)$$

236 This approximation might be helpful when information about the in-plane shear modulus G_{xy} is
 237 not available. Moreover, it is straightforward from Eq. (23) and Eq. (25) to determine the rate of
 238 change of the plate wavenumber with the frequency as:

$$239 \quad k_B(\phi) \frac{\partial k_B}{\partial \omega} = \frac{(k_{B,x} \cos \phi)^2 + (k_{B,y} \sin \phi)^2}{2\omega}. \quad (26)$$

240 The frequency dependent stiffness properties required as input data in both models here pre-
 241 sented can be derived from the bending wavenumbers $k_{B,x}$ and $k_{B,y}$ associated with the principal
 242 directions of the orthotropic plate.

243 3. Experimental measurements

244 Three different three-ply CLT plates, 4.2 m wide and 2.9 m high, were tested in Empa's
 245 wall sound insulation test facility. Even though all three panels are constituted by three plies of

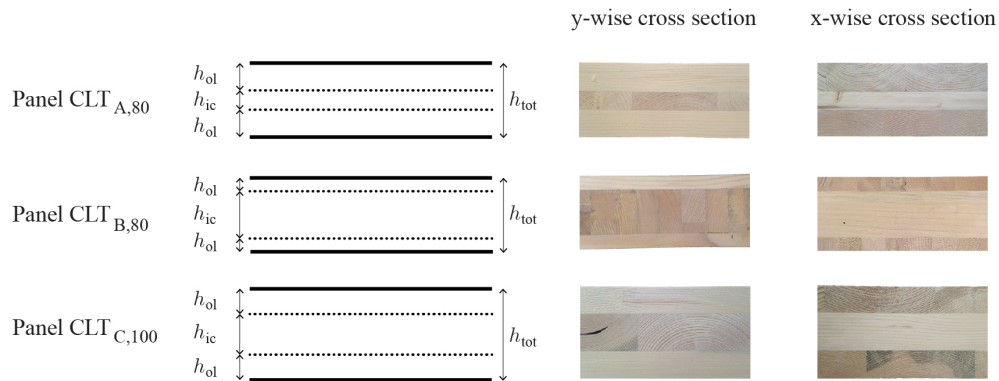


Figure 2: Investigated CLT panels: diagram of the layers and cross-sections along the principal directions.

246 wooden beams, there are differences either in the ratio between the thickness of the inner core
 247 and the outer layers, or in the total thickness, as shown in Figure 2. The geometric characteristics
 248 of the tested panels are summarised in Table 1. Each plate was mounted in a rigid frame between
 249 the two testing rooms. It was fixed and sealed using elastic putty along all the edges on both
 250 sides, as shown in Figure 3. In order to experimentally evaluate the plate's radiation efficiency,
 251 one has to measure the mean square velocity of the plate surface and the total radiated sound
 252 power. A Polytec PSV-500 laser scanning vibrometer was used to measure the vibration velocity
 253 on a 513 points grid on the plate surface. The CLT wall was excited by a B&K 4809 vibration
 254 exciter driven with a white noise signal, to reproduce a structure-borne point source. In order
 255 to excite a sufficient number of modes two different source positions were used, one after the
 256 other, their coordinates p_{S_1} and p_{S_2} are given for each panel in Table 1. A PCB impedance-head
 257 was attached to the shaker stinger in order to determine the driving point mechanical impedance
 258 by measuring both the input force and the acceleration, from which the plate loss factor was
 259 evaluated. The diffuse field sound pressure in the receiving room was measured using a B&K
 260 rotating boom microphone. The radiated sound power cannot be directly measured, but needs
 261 to be determined from other quantities, such as sound pressure, sound intensity or vibration
 262 velocity. The sound power radiated from the tested CLT plates was experimentally determined
 263 by two different approaches.

264 *Diffuse Field Approach (DFA)* – Assuming a perfectly diffuse sound field, the radiated sound
 265 power is determined from the mean square sound pressure $\langle p^2 \rangle_{s,t}$, measured in the central area
 266 of the room. To account for the higher energy density near the room boundaries, which affects
 267 results at low frequencies, the Waterhouse correction [40] has been applied and the radiated

Table 1: Plate and test facility geometric characteristics

	CLT _{A,80}	CLT _{B,80}	CLT _{C,100}
L_x (m)	4.20	4.20	4.20
L_y (m)	2.90	2.90	2.90
S (m ²)	12.18	12.18	12.18
h_{tot} (m)	0.080	0.080	0.100
h_{ol} (m)	0.030	0.015	0.030
h_{ic} (m)	0.020	0.050	0.040
ρ (kg/m ³)	484.4	467.2	484.4
m' (kg/m ²)	38.75	37.38	48.44
$p_{S_1} = (x(\text{m}), y(\text{m}))$	(0.5, 0.8)	(0.9, 1.2)	(0.5, 0.9)
$p_{S_2} = (x(\text{m}), y(\text{m}))$	(3.6, 0.9)	(3.2, 0.9)	(3.2, 1.2)

power was calculated using the equation:

$$W_{\text{rad}} = \frac{\langle p^2 \rangle_{s,t}}{4\rho_0 c_0} A \left(1 + \frac{S_T \lambda_0}{8V} \right). \quad (27)$$

The absorption area A is calculated from the measured reverberation time and the room volume V using the well known Sabine's relation, λ_0 is the acoustic wavelength and S_T is the total surface area of the receiving room. The main limitation of this approach is the diffuse field assumption, which is hardly achieved below 100 Hz in wall sound insulation laboratories, designed according to the standard ISO 10140-5 [41].

Discrete Calculation Method (DCM) – The radiated sound power was also evaluated by using the DCM, as:

$$W_{\text{rad}} = \sum_i \left[\text{Re}(Z_{ii}) |v_i|^2 + \sum_j \text{Re}(Z_{ij} v_i v_j^*) \right]. \quad (28)$$

DCM is a hybrid method, proposed by Hashimoto [42], which requires both numerical calculations and the complex vibration velocity, measured over a grid of points on the plate surface. The plate surface has to be discretised in small piston-like source elements. The radiated sound power is determined from the calculated self- and cross-radiation impedances Z_{ii} , Z_{ij} and from the measured complex vibration velocity v_i of each sub-element. A complete and detailed description of this method is given in the original paper by Hashimoto [42]. In this method, it is assumed that the panel is surrounded by an infinite rigid baffle and that sound is radiated into a semi-infinite half-space. Effects due to the room's geometry are neglected.

The experimental radiation efficiency of the orthotropic CLT plate was used to validate the prediction models described in the previous section. The structural wavenumbers associated with the plate's principal directions $k_{B,x}$ and $k_{B,y}$, given in one-third octave band values in Table 2 and shown in narrowband in Figure 4, were experimentally determined from a non-destructive measurement procedure based on wave propagation analysis, described in detail in [43]. They were used to determine the stiffness properties required as model input data. Moreover, the plate

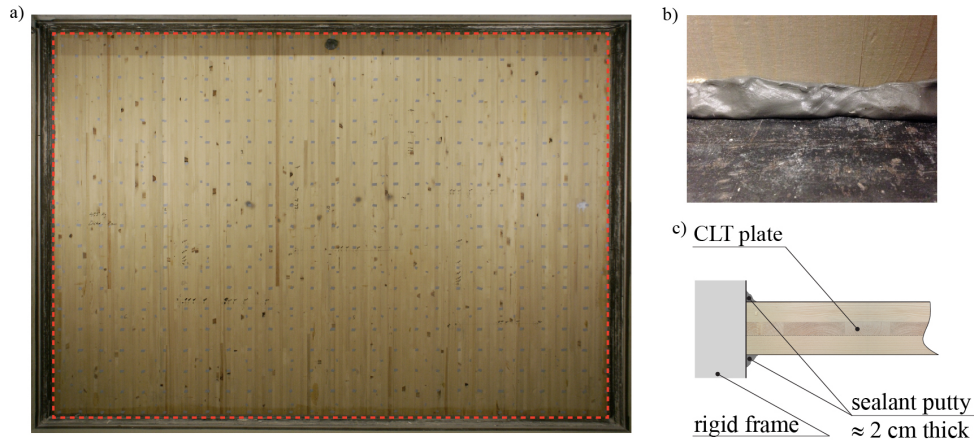


Figure 3: Experimental set-up: CLT plate mounted into a steel-concrete composite frame between the testing rooms of the sound transmission test facility.

292 damping can be taken into account, in both models, by means of complex input data [44]:

$$293 \quad \bar{D} = D(1 + i\eta), \quad (29)$$

294 where \bar{D} is the complex bending stiffness and η is the plate loss factor. The loss factor of the CLT
295 plate was determined using the power injection method, as described in [45–47] from point input
296 force and acceleration, measured with an impedance head attached to the shaker stinger. The
297 accuracy of this approach has been proven in several papers [48–50], in which it was compared
298 with other methods that can be used to determine the structural damping, such as the decay
299 response method, or the half-power bandwidth method.

300 4. Results

301 The two prediction models are validated in this section by comparing the numerical results
302 with the radiation efficiency experimentally measured for the three CLT plates. It is easier to
303 understand the theoretical background underlying these models by deriving first the more general
304 formulations and then simplifying the problem with more restrictive assumption. However, it is
305 more convenient to present the results the other way around. At first the modal-average approach
306 is considered, being the simplest and less computationally expensive; then the more accurate
307 analytical/modal approach is validated. In both cases the experimental radiation efficiency is
308 computed as the average of the results obtained from the DCM and the DFA approaches, which
309 provide in general consistent results. A thorough investigation of their reliability can be found in
310 [51], however, for sake of completeness, the panels' experimental radiation efficiency is plotted
311 together with the standard deviation between the two methods. It should be mentioned that the
312 DFA has not been applied below 100 Hz. It is shown that the experimental deviation between
313 different approaches, or different source positions, can be up to 2-3 dB.

Table 2: One-third octave bands values of the structural wavenumbers and loss factor used as input data to model the cross-laminated timber plates

f (Hz)	$k_{B,x,CLT_{A80}}$ (rad/m)	$k_{B,y,CLT_{A80}}$ (rad/m)	$k_{B,x,CLT_{B80}}$ (rad/m)	$k_{B,y,CLT_{B80}}$ (rad/m)	$k_{B,x,CLT_{C100}}$ (rad/m)	$k_{B,y,CLT_{C100}}$ (rad/m)	η (-)
100	4.6	2.4	3.5	3.0	3.4	2.1	0.08
125	5.2	2.7	4.0	3.4	3.8	2.4	0.08
160	6.0	3.1	4.6	3.9	4.3	2.8	0.07
200	6.6	3.4	5.1	4.3	4.8	3.1	0.07
250	7.5	3.9	5.9	4.9	5.5	3.6	0.07
315	8.5	4.4	6.7	5.5	6.2	4.1	0.06
400	9.7	5.1	7.7	6.3	7.0	4.8	0.05
500	11.0	5.8	8.8	7.1	8.0	5.6	0.04
630	12.6	6.7	10.3	8.1	9.2	6.6	0.03
800	14.4	7.7	12.0	9.3	10.6	7.9	0.03
1000	16.7	9.0	14.1	10.7	12.2	9.4	0.03
1250	19.3	10.6	16.8	12.5	14.2	11.5	0.03
1600	22.5	12.5	20.2	14.5	16.6	14.0	0.03
2000	26.5	15.0	24.6	17.1	19.6	17.3	0.03
2500	31.4	18.2	30.1	20.3	23.4	21.6	0.03

314 *4.1. Modal-average approach*

315 The modal-average radiation efficiency computed for the three CLT plates is presented in
 316 Figures 5,6 and 7, in terms of radiation index $L_\sigma = 10 \log \sigma$, in one-third octave bands. This
 317 statistical approach is validated by comparing the computed data with the radiation efficiency
 318 experimentally evaluated for each CLT panel by averaging the results obtained for the two shaker
 319 positions, thus no standard deviation is shown.

320 Orthotropic plates are characterised by a coincidence region limited by two coincidence fre-
 321 quencies, since the structural wave velocity depends on the propagation direction. The lowest
 322 coincidence frequency corresponds to the stiffest principal orthotropic direction and for CLT
 323 walls it is usually the vertical one, along which the outer layers' grains are oriented. As shown
 324 in the comparison in Figure 5, the predicted results well approximate the experimental radia-
 325 tion index measured for the plate $CLT_{A,80}$. The first coincidence, indicated by a peak where the
 326 curve gradient changes, is found within the 250 Hz band, even though in the simulated data this
 327 is not as pronounced as in the experimental results. The upper coincidence frequency, which
 328 also represents the critical condition, is generally related to the horizontal principal direction of
 329 a CLT wall, perpendicular to the grain of the outer layers and parallel to the orientation of the
 330 core fibres. The critical condition of the plate $CLT_{A,80}$ falls between the 800 Hz and 1000 Hz
 331 frequency bands. It is clearly identifiable by the curve maximum, which is more emphasised in
 332 the predicted radiation index than in the experimental results. Above the critical frequency the
 333 whole plate radiates sound like an ideal piston source and the radiation efficiency tends to unity.
 334 Similar findings have been obtained comparing calculated and measured results for the other two
 335 plates. The modal-average radiation efficiency computed for the plate $CLT_{B,80}$ provides a good
 336 approximation of the experimental trend, as shown in Figure 6. This panel exhibits a weaker
 337 orthotropy, with its first coincidence between the 250 Hz and 315 Hz frequency bands and the
 338 critical condition in the band centred around 500 Hz. A similar agreement is also found be-
 339 tween the simulated and experimental average-radiation efficiency of the plate $CLT_{C,100}$, shown
 340 in Figure 7. The first coincidence falls in the 200 Hz frequency band, and the critical condition

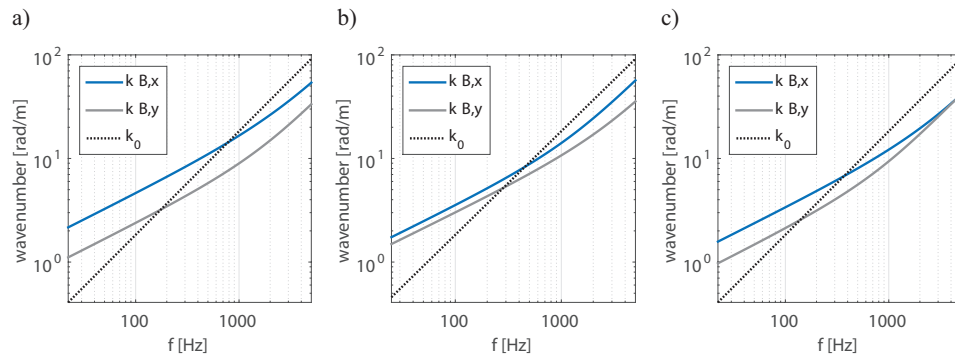


Figure 4: Structural wavenumbers along the principal directions used as input data to model the three CLT panels: (a) panel CLT_{A,80}; (b) panel CLT_{B,80}; (c) panel CLT_{C,100}

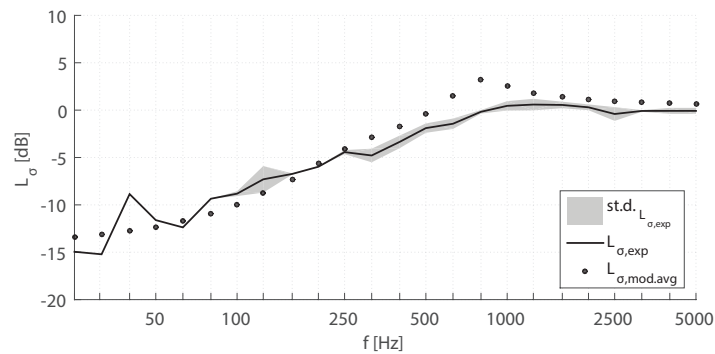


Figure 5: Panel CLT_{A,80}: the modal-average radiation index $L_{\sigma, \text{mod-avg}}$ is compared with the experimental results averaged over all the source positions $L_{\sigma, \text{exp}}$ in one-third octave bands.

341 is between the bands centred around 400 Hz and 500 Hz. Once again the numerical radiation
 342 efficiency well approximates the trend of the experimental data providing a smooth curve with
 343 the peak associated with the critical condition spread over different frequency bands and the first
 344 coincidence pinpointed by a change in the curve slope.

345 In general, such a statistical model allows to obtain a good approximation of the radiation
 346 efficiency trend in the considered frequency range, identifying with good accuracy the first co-
 347 incidence and the critical condition; although it cannot provide a very accurate and detailed pre-
 348 diction below the critical condition. The high modal density assumption, necessary to consider
 349 a continuous distribution of modes, is not sufficiently fulfilled within the entire frequency range,
 350 since below the critical condition the vibrational field of the CLT plate surface is not perfectly
 351 diffuse and only a few modes lay within the frequency bands. Moreover, the near-field generated
 352 around the excitation point represents a discontinuity, not considered by the model, which usu-
 353 ally enhance radiation. Nevertheless, the modal-average approach provides helpful insights on
 354 the radiation of the orthotropic CLT plate, even if it is not able to capture the modal behaviour

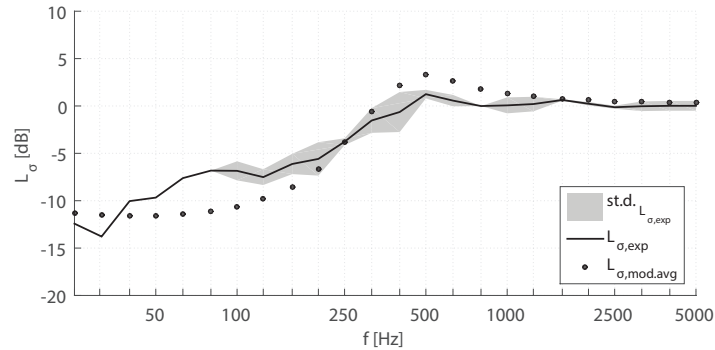


Figure 6: Panel $CLT_{B,80}$: the modal-average radiation index $L_{\sigma,mod-avg}$ is compared with the experimental results averaged over all the source positions $L_{\sigma,exp}$ in one-third octave bands.

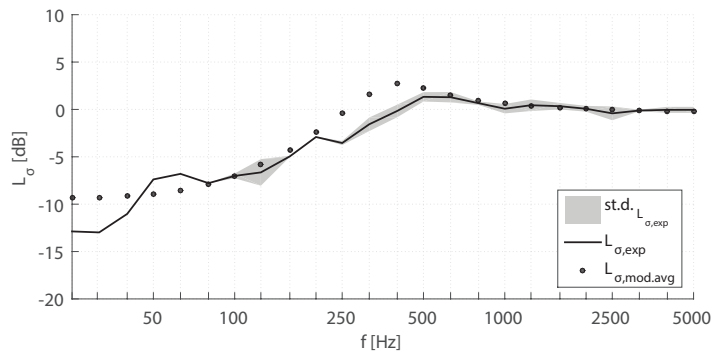


Figure 7: Panel $CLT_{C,100}$: the modal-average radiation index $L_{\sigma,mod-avg}$ is compared with the experimental results averaged over all the source positions $L_{\sigma,exp}$ in one-third octave bands.

355 below the critical frequency.

356 4.2. Modal / analytical approach

357 A vibro-acoustic model based on an modal/analytical approach has been implemented with
 358 the aim to obtain a more detailed prediction also in the frequency region characterised by a low
 359 mode count. Moreover, this approach also allows to take into account the influence of the fluid
 360 loading, even though the computation of the radiation impedance matrix requires a huge effort.
 361 However, the influence of fluid loading on the sound radiated by a CLT building panel is very
 362 small, as proven in Appendix B, since air has a much lower inertia compared to the investi-
 363 gated structures. Therefore, the radiation impedance can be approximated by the real part of
 364 the self-radiation resistance, neglecting fluid loading and reducing significantly the computa-
 365 tional cost of the algorithm. The model is validated by comparing the numerical results with the
 366 experimental CLT plates' radiation efficiency for each single shaker position. In Figure 8 the
 367 numerical and experimental results for the panel $CLT_{A,80}$ are compared. The graph (a), on the

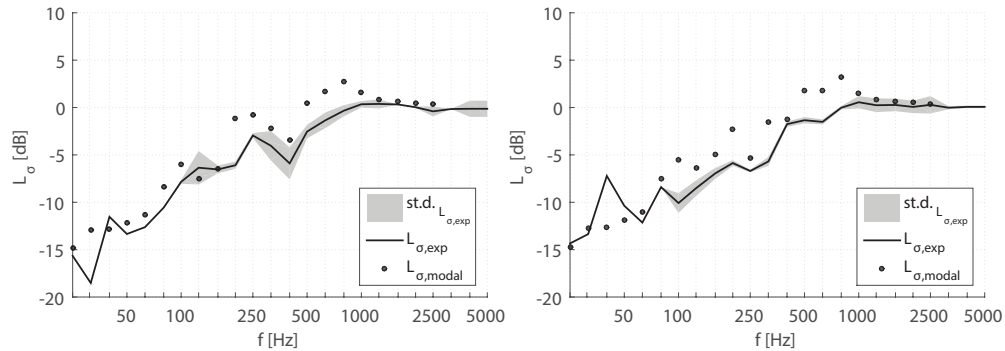


Figure 8: Panel CLT_{A,80}: modal based radiation index in one-third octave bands. Comparison between numerical results and experimental data: (a) plate mechanically excited at position p_{S_1} ; (b) plate mechanically excited at position p_{S_2} .

368 left-hand side, refers to source position p_{S_1} , while the graph (b) on the right-hand side is related
 369 to source position p_{S_2} . Given that experimental deviations can be up to 2-3 dB, the comparisons
 370 show good agreement between numerical and experimental results, despite the fact that the predicted
 371 radiation efficiency is overestimated in certain frequency bands with discrepancies up to
 372 5 dB. Below the critical condition the dips and peaks of experimental radiation efficiency are approximated
 373 with good accuracy by the predicted results. The comparison between the predicted and experimental radiation
 374 efficiency of the panel CLT_{B,80}, shown in Figure 9 highlights a good agreement. However, as for the previous panel,
 375 the simulated radiation efficiency is, in certain bands, slightly overestimated or some peaks associated with the
 376 structural resonant modes can be shifted towards neighbouring frequency bands. The same conclusions can be
 377 drawn from the comparison between numerical and experimental radiation efficiency of the panel CLT_{C,100},
 378 given in Figure 10. In this case slightly larger discrepancies are found, especially in the very low
 379 frequencies, but still the numerical radiation efficiency well approximates the measured data.
 380

381 It should be noted that the spread in the experimental radiation efficiency, expressed as standard
 382 deviation, is for some frequency band significant and comparable to the difference between
 383 measured and predicted results. Moreover, below the upper coincidence frequency, i.e. the critical
 384 condition, the sound is mainly radiated from the plate discontinuities, such as the boundaries.
 385 The real mounting conditions, described in section 3, are much more complex than the simply-
 386 supported boundaries assumed in the model: at the bottom edge the plate is supported by a
 387 rigid frame whereas at all the other edges there is a small gap, sealed with elastic putty. These
 388 edge mountings cannot completely prevent the out-of-plane translational motion of the plate, as
 389 required by the assumption of simply-supported boundaries, resulting as a lower degree of restraint.
 390 The difference between theoretical and real boundary conditions is the main cause of the
 391 discrepancies between predicted and experimental radiation efficiency. In fact, according to a
 392 recent study presented by Squicciarini et al. [52], in which the radiation efficiency of a plate with
 393 different combinations of boundary condition was investigated, differences up to 25 dB can be
 394 found between totally free and simply-supported boundaries. The study highlights the general
 395 trend of a diminishing radiation efficiency as the degree of restraint at the edges decreases. A
 396 more rigorous model, considering mixed boundary conditions with translational and rotational

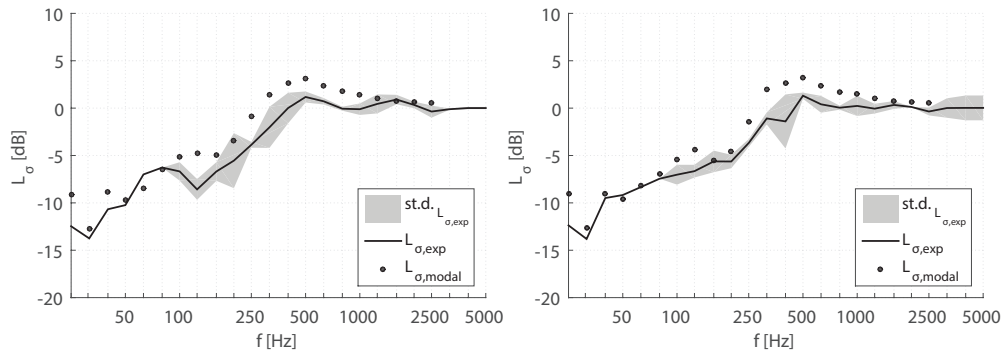


Figure 9: Panel CLTB,80: modal based radiation index in one-third octave bands. Comparison between numerical results and experimental data: (a) plate mechanically excited at position p_{S_1} ; (b) plate mechanically excited at position p_{S_2} .

397 springs with very uncertain and locally varying stiffness, would require a tremendous effort that
 398 would not have practical applicability. Therefore, in order to develop a usable tool for building
 399 acoustics design, simply-supported boundaries have been considered, since they allow for an
 400 analytical closed solution reducing the algorithm's computational cost.

401 4.3. Comparison between the two models

402 The results obtained from the two models presented provide constant results in reasonably
 403 good agreement with the experimental data. However, in both cases some discrepancies were
 404 found, either in the low frequency range, or at higher frequencies where the models seems to
 405 slightly overestimate the radiation index around the critical condition. This effect, which was also
 406 observed in an analogous investigation of sound transmission loss of CLT panels [53], is probably
 407 related to the damping of the system, even though it was taken into consideration in the models by
 408 means of a complex stiffness, as given in Eq. (29). However, for a complete understanding of the
 409 problem a further investigation is required in future works. A last comparison is made between the
 410 results obtained from the two different prediction approaches. In Figure 11 a), the modal-
 411 average radiation index $L_{\sigma,mod,avg}$ of the plate CLTA,80 is compared, in one-third octave bands,
 412 to the two radiation indexes, computed by using a modal/analytical approach for each source
 413 position used in the experiments: $L_{\sigma,modal,S_1}$ and $L_{\sigma,modal,S_2}$. While the two models provide a
 414 consistent trend, the modal-based radiation indexes associated with the two excitation sources
 415 highlight peaks and dips associated with the structural modes up to approximately 500 Hz. In
 416 order to consider a higher number of modes excited in the plate, the modal radiation index of the
 417 panel CLTA,80, was averaged over 100 non-simultaneous source positions, randomly chosen over
 418 the plate surface. In Figure 11 b), the modal radiation index averaged over 100 source positions
 419 $L_{\sigma,mod,100}$ is compared to the statistical results $L_{\sigma,mod,avg}$. By increasing the number of excited
 420 modes the structural modal behaviour is noticeable only up to the 250 Hz band, while at higher
 421 frequencies the radiation curve smooths out. Moreover, the statistical radiation index seems to
 422 underestimate the results obtained from the modal approach within all the frequency bands below
 423 the critical condition, in all probability due to the low mode count in this frequency range.

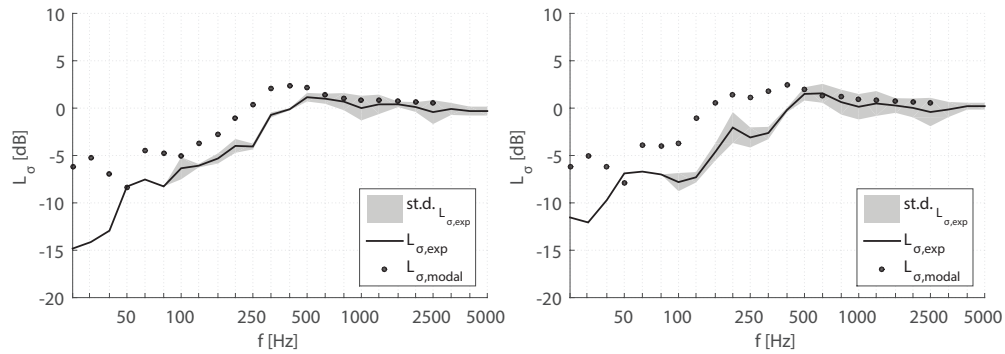


Figure 10: Panel CLT_{C,100}: modal based radiation index in one-third octave bands. Comparison between numerical results and experimental data: (a) plate mechanically excited at position p_{S_1} ; (b) plate mechanically excited at position p_{S_2} .

424 The modal-average approach is a handy computationally efficient tool, for preliminary inves-
 425 tigations, in order to obtain information on the radiation trend, or on the coincidence frequencies
 426 of an orthotropic panel. However, it may lead to underestimated results if the mode count within
 427 a certain frequency band is low, since the basic assumption of high modal density is not fulfilled.
 428 In this case, a more accurate approximation of the radiation efficiency can be obtained by means
 429 of a modal approach which considers all the modes actually excited by the source, even though
 430 it requires a greater computational effort.

431 5. Conclusion

432 Two models to evaluate the radiation efficiency of a CLT panel, developed with different
 433 approaches, have been presented. In both models the panel is assumed to be a baffled thin or-
 434 thotropic plate with simply supported boundary conditions, excited by a broad band, mechanical
 435 force. These models have been validated with the experimental radiation efficiency of three
 436 mechanically-excited three-ply cross-laminated timber plates, which was determined by using
 437 two different methods to evaluate the total radiated sound power: the diffuse field approach
 438 (DFA) and the discrete calculation method (DCM), which provided consistent results.

439 A modal-average approach provides a good approximation of the radiation efficiency trend.
 440 However, if the vibrational field is not diffuse, but only few modes exist within a frequency band,
 441 it is not suitable for an accurate prediction below the critical condition, since some of the basic
 442 assumptions the model is based on, such as high modal density and continuous distribution of
 443 modes, are not fulfilled within this frequency range. Nevertheless, it still represents a simple
 444 and useful tool to perform preliminary analysis on orthotropic plates during the design process.
 445 The two shaker positions used to experimentally evaluate the CLT panel's radiation efficiency
 446 provided results significantly different in the low frequency range. It should be noted that in-
 447 situ building walls can be excited by multiple and rather complex sources simultaneously; this
 448 condition would thus extend towards lower frequencies the range in which the assumption of
 449 diffuse vibrational field is fulfilled.

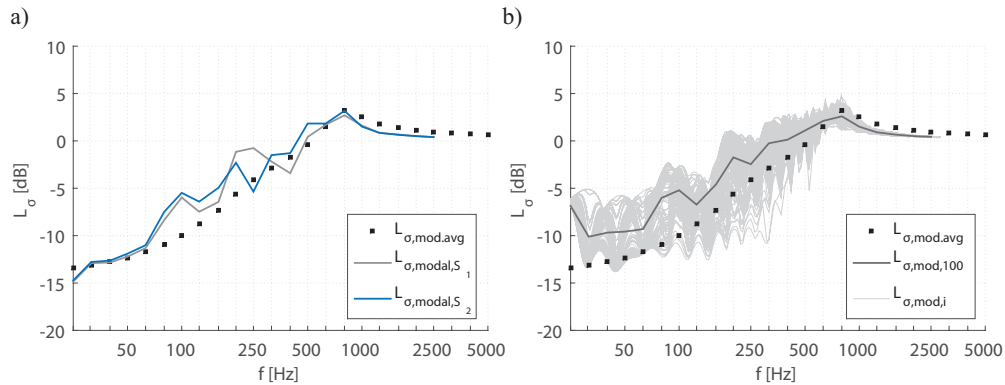


Figure 11: Comparison between the two different approaches: a) the radiation index obtained from modal average approach is compared with the radiation indexes computed with the modal/analytical approach for the two source positions; b) the radiation index obtained from modal average approach is compared with the radiation index, obtained using the modal approach and averaged over 100 source positions.

450 For a more accurate and detailed prediction of the radiation efficiency of orthotropic plates,
 451 even below the critical condition, a modal/analytical approach has been presented. The assump-
 452 tion of simply-supported boundaries allows for an analytical or approximated closed solution of
 453 most of the integral equations involved in the model, providing a fast algorithm. Moreover, the
 454 influence of the fluid loading on the sound radiated in the surrounding air by a CLT panel has
 455 been proven to be very small. It can thus be neglected by approximating the radiation impedance
 456 with the real part of the self radiation resistance, reducing significantly the computational cost
 457 of the algorithm. A good agreement between predicted and experimental results was found, al-
 458 though the model slightly overestimates the radiation efficiency experimentally evaluated for the
 459 tested CLT plate, particularly below the critical condition. Boundary conditions have a signifi-
 460 cant influence on sound radiation in this frequency range. In fact, these discrepancies are mostly
 461 due to the difference between the constraint provided by the real mounting conditions and the
 462 idealised simply supported boundaries. However, the simply-supported boundaries assumption
 463 allows one to obtain a sufficiently good approximation of the radiation efficiency in a reasonable
 464 time. The modal / analytical approach requires a greater computational effort compared to the
 465 statistical model, but it provides an accurate approximation of the radiation efficiency of a CLT
 466 panel even below the critical condition, where such a structure is characterised by a rather low
 467 modal density. Further uncertainty can possibly be due to the experimental wavenumbers used
 468 as input data for the material's elastic properties. However, the agreement highlighted by the
 469 presented results proved that by means of frequency dependent properties it is possible to treat
 470 complex structures, such as CLT panels, as homogeneous elements. The structural wavenum-
 471 bers can be experimentally determined in a number of ways. The determination of the structural
 472 wavenumber, or at least of its real part, seems straightforward if compared to the effort required
 473 in order to determine all the characteristics that would be necessary to consider otherwise, such
 474 as the properties of wooden beams and their connection within each ply as well as the coupling
 475 between the different plies that constitute the CLT panel.

476 **Acknowledgement**

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 478 *Empa - Swiss Federal Laboratories for Material Science and Technology - Laboratory for Acous-*
 479 *tics/Noise Control.*

480 **Appendix A. Stiffness matrix**

In this paragraph the equation to compute the stiffness matrix coefficients is derived for the case of simply-supported boundary conditions. Using the dimensionless coordinates:

$$\begin{cases} u = \frac{x}{L_x}; \\ v = \frac{y}{L_y}. \end{cases}$$

481 Eq. (9) is rewritten in terms of the new spatial coordinates u and v :

$$\begin{aligned} K_{mnpq} = & L_x L_y \int_0^1 \int_0^1 \left[D_x \left(\frac{1}{L_x^2} \right)^2 \frac{\partial^2}{\partial u^2} \psi_{mn}(u, v) \frac{\partial^2}{\partial u^2} \psi_{pq}(u, v) \right. \\ & + D_y \left(\frac{1}{L_y^2} \right)^2 \frac{\partial^2}{\partial v^2} \psi_{mn}(u, v) \frac{\partial^2}{\partial v^2} \psi_{pq}(u, v) \\ & + \nu_{yx} D_x \left(\frac{1}{L_y L_x} \right)^2 \frac{\partial^2}{\partial u^2} \psi_{mn}(u, v) \frac{\partial^2}{\partial v^2} \psi_{pq}(u, v) \\ & + \nu_{xy} D_y \left(\frac{1}{L_y L_x} \right)^2 \frac{\partial^2}{\partial v^2} \psi_{mn}(u, v) \frac{\partial^2}{\partial u^2} \psi_{pq}(u, v) \\ & \left. + 4G_{xy} \frac{h^3}{12} \left(\frac{1}{L_y L_x} \right)^2 \frac{\partial^2}{\partial u \partial v} \psi_{mn}(u, v) \frac{\partial^2}{\partial u \partial v} \psi_{pq}(u, v) \right] dv du, \end{aligned} \quad (\text{A.1})$$

the mode shape functions for simply-supported boundaries are given in the new coordinate system as:

$$\begin{cases} \psi_{mn}(u, v) = \sin(m\pi u) \sin(n\pi v); \\ \psi_{pq}(u, v) = \sin(p\pi u) \sin(q\pi v). \end{cases}$$

483 Due to the orthogonal property of the basis functions Eq. (A.1) can be reduced to:

- 484 • if $m = p$ and $n = q$

$$K_{mnpq} = K_{mn} = \frac{L_x L_y}{4} \left[D_x \frac{m^4 \pi^4}{L_x^4} + D_y \frac{n^4 \pi^4}{L_y^4} + 2B \frac{m^2 n^2 \pi^4}{L_x^2 L_y^2} \right]; \quad (\text{A.2})$$

- 486 • if $m \neq p$ and $n \neq q$

$$K_{mnpq} = 0. \quad (\text{A.3})$$

488 The stiffness matrix is hence diagonal and can be computed as an algebraic equation, significantly
 489 reducing the computational time.

490 The apparent bending stiffness along each principal i -direction D_i is obtained according to
 491 Eq. (3) from the experimental wavenumbers $k_{B,x}$ and $k_{B,y}$ given in Table 2. The in-plane shear
 492 modulus G_{xy} of the orthotropic plate, necessary to compute the effective torsional stiffness B
 493 given in equation (4), has been approximated as a function of the elastic moduli associated with
 494 the principal directions [32] as:

$$495 \quad G_{xy} = \frac{\sqrt{E_x E_y}}{2 \left(1 + \sqrt{\nu_{xy} \nu_{yx}} \right)}. \quad (\text{A.4})$$

496 The value of the elastic properties ν_{xy} and ν_{yx} , has been determined by considering Eq. (5) and
 497 assuming the Poisson's ratio $\nu = \sqrt{\nu_{xy} \nu_{yx}} = 0.3$ as typical for wood materials. The apparent
 498 frequency dependent elastic properties E_x and E_y have been derived from the bending stiffness
 499 along the principal directions D_x and D_y according to Eq. (3).

500 Appendix B. Radiation impedance matrix

For a simply-supported baffled plate, the four-fold integral equation to compute the radiation
 impedance given in Eq. (13) is reduced to a double integral by using the approximation proposed
 by Sandman [4] and Nellisse [6]. A first coordinate transform is applied:

$$\begin{cases} \alpha = \frac{x}{L_x}; \\ \beta = \frac{y}{L_y}; \end{cases} \quad \begin{cases} \bar{\alpha} = \frac{\bar{x}}{L_x}; \\ \bar{\beta} = \frac{\bar{y}}{L_y}; \end{cases} \quad r = \frac{L_x}{L_y}.$$

501 After the mode mixing the radiation impedance results:

$$502 \quad Z_{mnpq} = i\omega\rho_0 S^2 \int_0^1 \int_0^1 \int_0^1 \int_0^1 \psi_{mp}(\alpha, \bar{\alpha}) G(\alpha, \beta, 0, \bar{\alpha}, \bar{\beta}, 0) \psi_{nq}(\beta, \bar{\beta}) d\bar{\alpha} d\bar{\beta} d\alpha d\beta. \quad (\text{B.1})$$

To reduce the four-fold integral another change of variable is needed:

$$\begin{cases} u = \alpha - \bar{\alpha}; \\ v = \bar{\alpha}; \end{cases} \quad \begin{cases} \bar{u} = \beta - \bar{\beta}; \\ \bar{v} = \bar{\beta}. \end{cases}$$

503 Considering the symmetry of the mode shape functions, the radiation impedance can be ex-
 504 pressed as:

$$505 \quad Z_{mnpq} = i\omega\rho_0 4S^2 \int_0^1 \int_0^1 \Phi_{mp}(u) G(u, 0, \bar{u}, 0) \Phi_{nq}(\bar{u}) d\bar{u} du, \quad (\text{B.2})$$

506 where:

$$\begin{aligned}\Phi_{mp}(u) &= \int_0^{1-u} \sin(m\pi(u+v)) \sin(p\pi v) dv; \\ \Phi_{nq}(\bar{u}) &= \int_0^{1-\bar{u}} \sin(n\pi(\bar{u}+\bar{v})) \sin(q\pi\bar{v}) d\bar{v};\end{aligned}\tag{B.3}$$

$$G(u, 0, \bar{u}, 0) = \frac{\exp\left(-ik_0 L_x \sqrt{u^2 - r^{-2}(\bar{u})^2}\right)}{2\pi L_x \sqrt{u^2 - r^{-2}(\bar{u})^2}}.$$

508 Seeking a solution for the integral functions $\Phi_{mp}(u)$ and $\Phi_{nq}(\bar{u})$ it is possible to write:

- 509 • if $m = p$ and $n = q$:

$$\begin{aligned}\Phi_{mp}(u) &= \frac{\sin(\pi m(u-2))}{4\pi m} + \frac{\sin(\pi mu)}{4\pi m} + \cos(\pi mu) \left(\frac{1-u}{2}\right); \\ \Phi_{nq}(\bar{u}) &= \frac{\sin(\pi n(\bar{u}-2))}{4\pi n} + \frac{\sin(\pi n\bar{u})}{4\pi n} + \cos(\pi n\bar{u}) \left(\frac{1-\bar{u}}{2}\right).\end{aligned}\tag{B.4}$$

- 511 • if $m \neq p$ and $n \neq q$:

$$\begin{aligned}\Phi_{mp}(u) &= \frac{\sin(\pi(m-p+pu))}{2\pi(m-p)} - \frac{\sin(\pi mu)}{2\pi(m-p)} - \frac{\sin(\pi(m+p-pu))}{2\pi(m+p)} + \frac{\sin(\pi mu)}{2\pi(m+p)}; \\ \Phi_{nq}(\bar{u}) &= \frac{\sin(\pi(n-q+q\bar{u}))}{2\pi(n-q)} - \frac{\sin(\pi n\bar{u})}{2\pi(n-q)} - \frac{\sin(\pi(n+q-q\bar{u}))}{2\pi(n+q)} + \frac{\sin(\pi n\bar{u})}{2\pi(n+q)};\end{aligned}\tag{B.5}$$

513 Applying Prosthaphaeresis' sum to product formulas, Eq. (B.5) and Eq. (B.4) can be reformu-
514 lated as:

- 515 • if $m = p$ and $n = q$:

$$\begin{aligned}\Phi_{mp}(u) &= \frac{1}{\pi} \left\{ \frac{\cos\left(\frac{\pi(m-p)}{2} + \frac{\pi(m+p)u}{2}\right) \sin\left(\frac{\pi(m-p)}{2} - \frac{\pi(m-p)u}{2}\right)}{m-p} \right. \\ &\quad \left. - \frac{\cos\left(\frac{\pi(m+p)}{2} + \frac{\pi(m-p)u}{2}\right) \sin\left(\frac{\pi(m+p)}{2} - \frac{\pi(m+p)u}{2}\right)}{m+p} \right\}; \\ \Phi_{nq}(\bar{u}) &= \frac{1}{\pi} \left\{ \frac{\cos\left(\frac{\pi(n-q)}{2} + \frac{\pi(n+q)\bar{u}}{2}\right) \sin\left(\frac{\pi(n-q)}{2} - \frac{\pi(n-q)\bar{u}}{2}\right)}{n-q} \right. \\ &\quad \left. - \frac{\cos\left(\frac{\pi(n+q)}{2} + \frac{\pi(n-q)\bar{u}}{2}\right) \sin\left(\frac{\pi(n+q)}{2} - \frac{\pi(n+q)\bar{u}}{2}\right)}{n+q} \right\};\end{aligned}\tag{B.6}$$

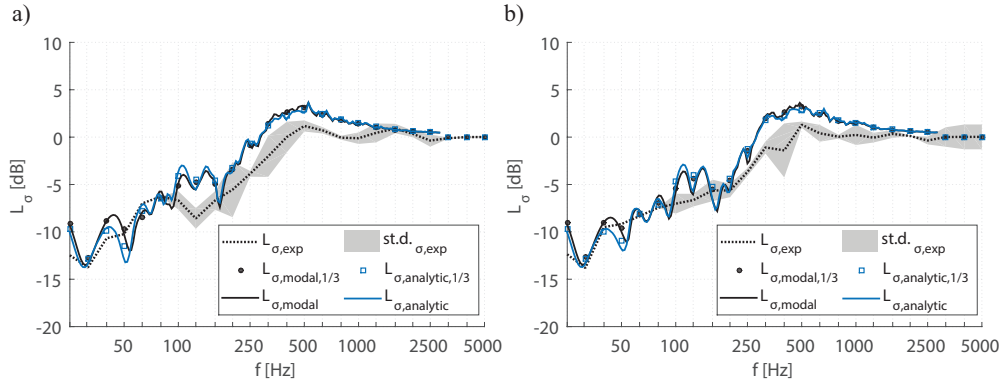


Figure B.12: Comparison between radiation efficiency of the panel $CLT_{B,80}$ either computed considering the radiation impedance coefficients Z_{mnpq} and its approximation with the self radiation resistance coefficients R_{mn} : (a) plate mechanically-excited at position p_{S_1} ; (b) plate mechanically-excited at position p_{S_2} .

- 517 • if $m = p$ and $n = q$:

$$\begin{aligned} \Phi_{mp}(u) &= \frac{1}{2\pi m} [\sin(\pi m(u-1)) \cos(-\pi m)] + \cos(\pi mu) \left(\frac{1-u}{2} \right); \\ \Phi_{nq}(\bar{u}) &= \frac{1}{2\pi n} [\sin(\pi n(\bar{u}-1)) \cos(-\pi n)] + \cos(\pi n\bar{u}) \left(\frac{1-\bar{u}}{2} \right). \end{aligned} \quad (B.7)$$

518

519 The radiation indices, computed considering both the full radiation impedance matrix Z_{mnpq} ,
 520 indicated as $L_{\sigma,analytic}$, and its approximation with the self-radiation resistance R_{mn} , $L_{\sigma,modal}$, are
 521 compared in narrow band in Figure B.12 for two positions of the mechanical point excitation,
 522 only the panel $CLT_{B,80}$, since it has the lowest surface mass. At low frequencies fluid loading
 523 has a small influence on sound radiated by a CLT plate and it is even smaller in the mid-high
 524 frequency range. We can conclude that although CLT panels are lightweight elements compared to
 525 the traditional building partitions, their inertia is still several orders of magnitude larger than
 526 the one provided by air, thus the load of the fluid does not affect significantly the plate dynamics.

527 **Appendix C. Near-coincidence frequency range: $\mu \approx 1 \pm \delta$**

528 In order to compute the modal-average radiation efficiency it is necessary to define three re-
 529 gions for which Leppington's equations are defined. In the implemented algorithm these intervals
 530 are not set a priori, instead all the three curves are computed for each investigated propagation
 531 direction ϕ . The function defined in the *above-coincidence* (*ac*) range assumes negative values
 532 below the critical condition while it is positive and tends asymptotically to unity above. The func-
 533 tion defined in the *below-coincidence* (*bc*) region presents a discontinuity at the first coincidence
 534 where $\mu = 1$. The first formulation presented by Leppington could not solve this singularity for
 535 $\mu = 1$, but some years later he proposed an integral formulation for a positive and continuous
 536 function valid within a region around the coincidence frequency, the *near-coincidence* (*nc*) inter-
 537 val. The cut-off frequency between the *bc* and *nc* regions is identified by the intersection which

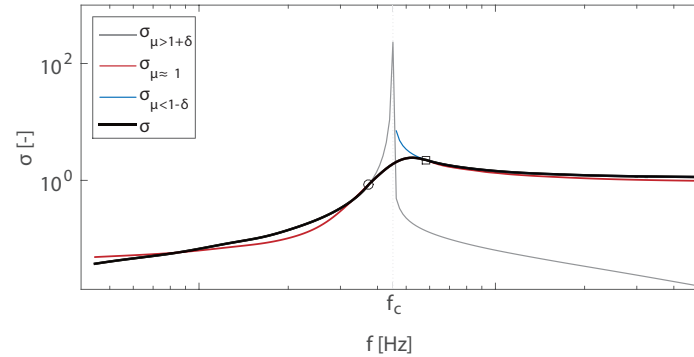


Figure C.13: Determination of the average radiation efficiency for a single propagation direction by combining the curves defined in each frequency region: below-coincidence, near-coincidence, above-coincidence;

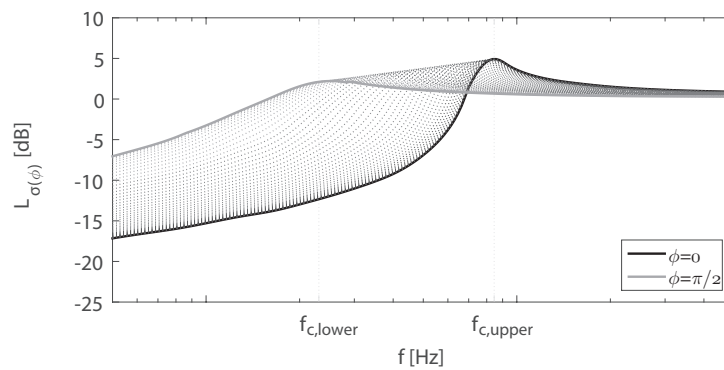


Figure C.14: Frequency dependent average radiation index for different propagation angles ϕ .

538 is the closest to the discontinuity of the bc function. The first intersection between the nc func-
 539 tion and the ac positive curve represents the limit between these two regions. It might happen
 540 that, due to numerical reasons, two curves do not intersect each other, even though the transition
 541 between two regions occurred. In this case the implemented algorithm evaluates the frequency
 542 at which the two functions are closest to each other. Once those limits are defined the resulting
 543 radiation efficiency is determined, for each investigated angle, by combining the three curves
 544 within the frequency range in which they are respectively defined. In Figure C.14 the radiation
 545 index is plotted, from $\phi = 0$ to $\phi = \pi/2$ at steps of $\Delta\phi = \pi/90$. The radiation efficiency with the
 546 lowest coincidence frequency is determined for the bending wave propagating along the stiffest
 547 direction, while the curve with the highest critical frequency is associated with the orthogonal
 548 direction. In other words the critical condition is shifted towards lower frequencies as the plate
 549 stiffness increases.

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